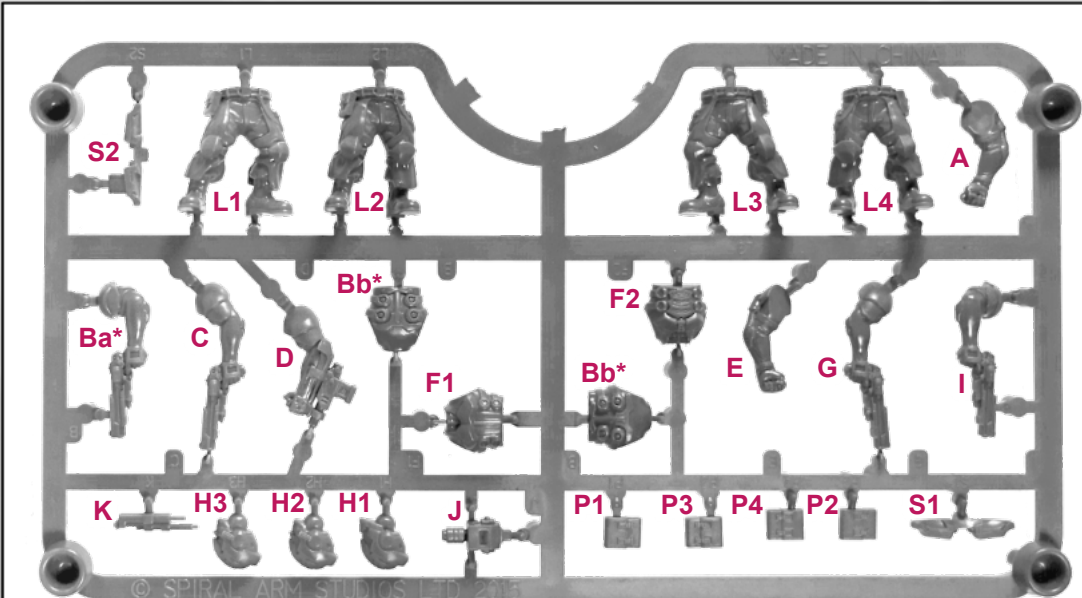


EPIRIAN BOT HANDLERS

Preparation: We recommend using sharp clippers to remove parts from the frame. Pulling parts from the sprue without clipping may result in damage to delicate parts. Use a hobby knife, seam scraper or file to remove any mould lines or frame joint nubs left by the clippers.

Assembly: For best results, use plastic glue (polystyrene cement).



This kit contains parts to build two Apprentice Handlers, or one Apprentice and one Journeyman Handler.

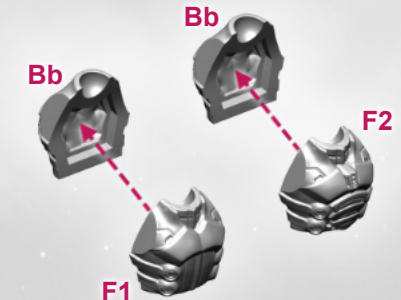
PARTS LIST

A	Right arm - tactile neural interface	H1-3	Head (x3)
Ba*	Left arm - pistol A	I	Right arm - pistol A
Bb*	Torso back (x2)	J	Command unit base
C	Left arm - pistol B	K	Command unit antenna
D	Left arm - auxiliary grenade launcher	L1-4	Legs (x4)
E	Left arm - tactile neural interface	P1-4	Pouches (x4)
F1-2	Torso front (x2)	S1-2	BotCom link (x2)
G	Right arm - pistol B		
Base 1	MEBS01 - 25mm Round Base	Base 2	MEBS02 - 28mm Round Base

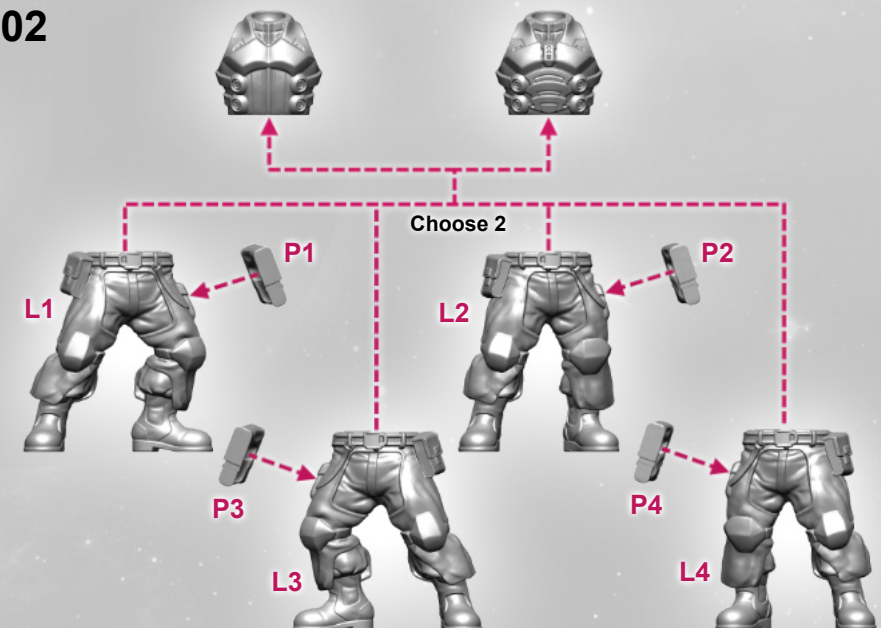
* These parts are both labelled on the sprue as 'B' due to a production error.



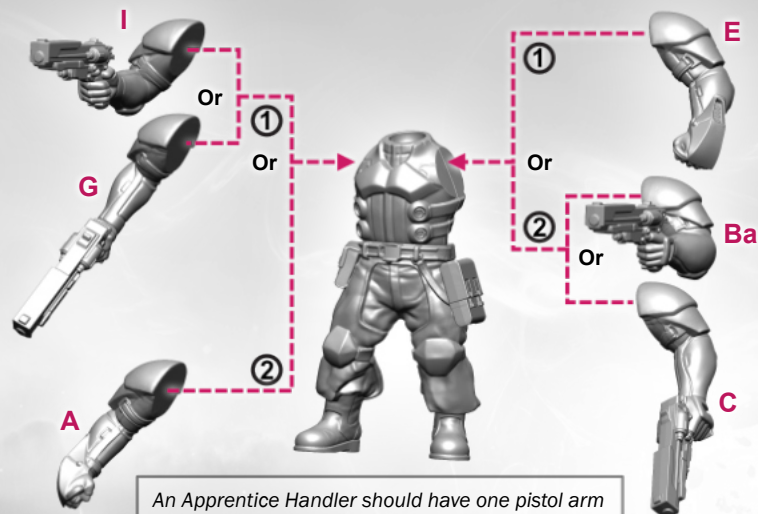
01



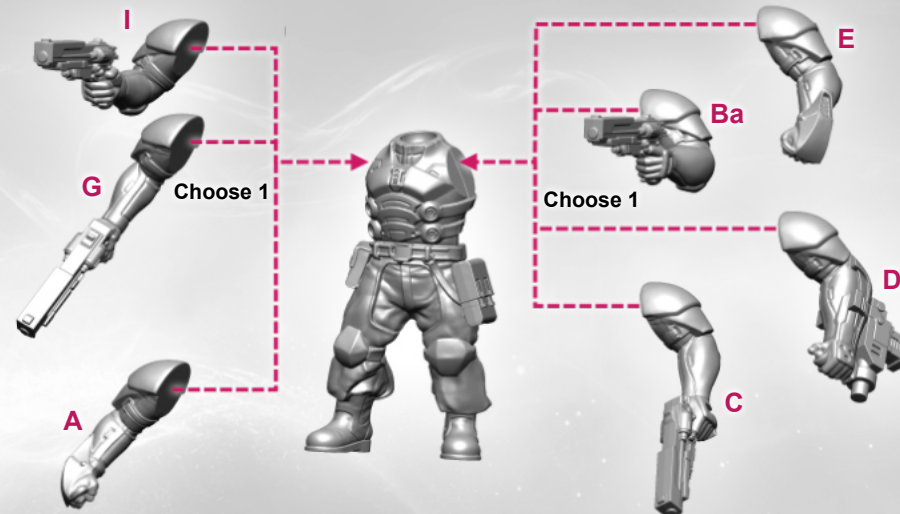
02



03a APPRENTICE HANDLER

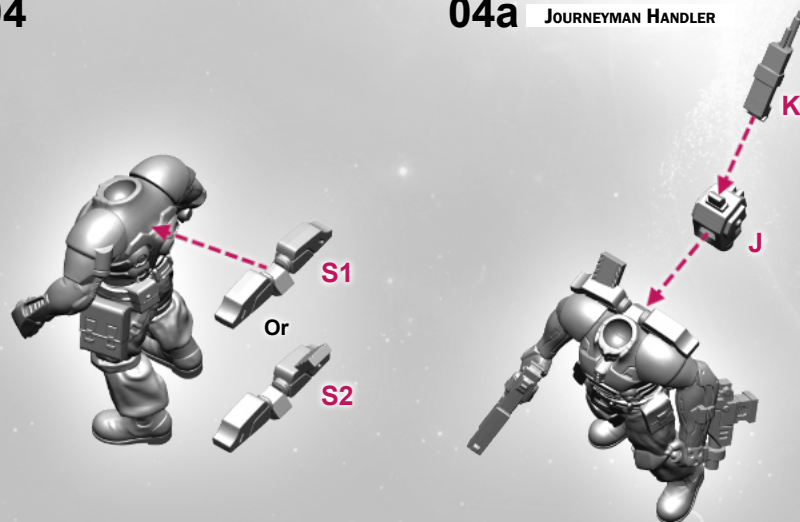


03b JOURNEYMAN HANDLER



04

04a JOURNEYMAN HANDLER



05

